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Introduction

$$\text{ODE: } \begin{cases} \dot{x}(t) = b(x(t)) \\ x(0) = x_0 \end{cases}$$

$b: \mathbb{R}^n \rightarrow \mathbb{R}^n$ is a smooth vector field trajectory
 $x: [0, \infty) \rightarrow \mathbb{R}^n$ is the time-dependent, solution of the system
 $x(t)$ is the state of the system at time $t \geq 0$.

Illustration:

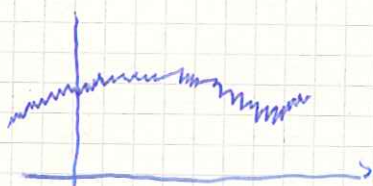


The solution is also smooth (for b smooth enough)

$$x(t) = x_0 + \int_0^t b(x(t)) dt$$

Model for smooth trajectory. For example a solar system
 • A ball you launched
 • etc.

There is other class of problems where the solution seems to follow an ODE, but with random perturbation



This can't be modelled by an ODE because the trajectory is not smooth and there is no randomness in an ODE

We need to add this randomness somehow to the system

$$\begin{cases} \dot{x}(t) = b(x(t)) + \underbrace{B(x(t)) \xi(t)}_{\text{random part}} \\ x(0) = x_0 \end{cases}$$

$B: \mathbb{R}^n \rightarrow \mathbb{R}^{n \times m}$, $\xi: \mathbb{R} \rightarrow \mathbb{R}^m$ is the m -dimensional white-noise

We need to define what this white noise is.

In the case

$$\begin{cases} \dot{X} = \xi(t) \\ X(0) = 0 \end{cases}, \text{ the solution is } X(t) = W(t), \text{ the } n \text{ dimensional } \underline{\text{Brownian motion.}}$$

That is $\xi(t) = \dot{W}(t)$

$$\Rightarrow \frac{dX}{dt} = b(X(t)) + B(X(t)) \frac{dW}{dt}$$

$$\Rightarrow \text{(SDE)} \begin{cases} dX(t) = b(X(t)) dt + B(X(t)) dW(t) \\ X(0) = x_0 \end{cases}$$

dX, dW are called stochastic differentials

$X(t)$ solves the SDE if $X(t) = x_0 + \underbrace{\int_0^t b(X(s)) ds}_{\text{well defined}} + \underbrace{\int_0^t B(X(s)) dW}_{\text{what does it mean?}}$ $t > 0$

Itô's chain rule: let $n=m=1$. let X_t be such that

$$dX = b(X)dt + c(X)dW$$

let $u: \mathbb{R} \rightarrow \mathbb{R}$ a smooth function. let $Y(t) = u(X(t))$

What is dY ?

In the deterministic case: $dY = u'(X)dX = u'(X)b(X)dt + u'(X)c(X)dW$

max This is not true however in our case because $dW \approx (dt)^{1/2}$

$$Y + dY = u(X + dX) = Y + u'(X)dX + \frac{1}{2}u''(X)(dX)^2 + \dots$$

$$dY = u'(X)dX + \frac{1}{2}u''(X)(dX)^2 + \dots$$

$$= u'(bdt + cdW) + \frac{1}{2}u''(bdt + cdW)^2 + \dots$$

$$= u'(bdt + cdW) + \frac{1}{2}u''(b^2dt^2 + 2bcdWdt + c^2dW^2) + \dots$$

$$= (u'(b) + \frac{1}{2}u''c^2)dt + u'(c)dW + O(dt^{3/2})$$

$$\boxed{dY = (u'(X)b + \frac{c^2}{2}u''(X))dt + cu'(X)dW}$$

Ex: $\begin{cases} dY = YdW \\ Y(0) = 1 \end{cases}$ Then $Y(t) = e^{W(t) - \frac{t}{2}}$

let $X = -\frac{t}{2} + W(t)$

That is $dX = -\frac{1}{2}dt + dW$

$\Rightarrow b = -\frac{1}{2}, c = 1$

let $u(X) = e^X$

Then $dY = dY = \underbrace{(e^X(-\frac{1}{2}) + \frac{1}{2}e^X)}_{=0} dt + e^X dW = Y(t) dW$

Ex let $S(t)$ be the price of a stock at time $t > 0$.

The relative change of price $\frac{dS}{S} = \mu dt + \sigma dW$, where $\mu > 0$ is the drift and σ the volatility.

volatility: degree of variation of stock price

drift: The expected return

$$\Rightarrow \begin{cases} dS = \mu S dt + \sigma S dW \\ S(0) = S_0 \end{cases}$$

(that is S_0 is the starting price)

Then $(t) = S_0 e^{\sigma W(t) + (\mu - \frac{\sigma^2}{2})t}$

Let $X(t) = \sigma W(t) + (\mu - \frac{\sigma^2}{2})t$. Then $dX = (\mu - \frac{\sigma^2}{2})dt + \sigma dW$

Let $v(X) = e^X$

$$\Rightarrow b = \mu - \frac{\sigma^2}{2}, \quad c = \sigma$$

Then $d\$ = dv(X) = (e^X(\mu - \frac{\sigma^2}{2}) + \frac{\sigma^2}{2} e^X)dt + \sigma e^X dW$

$$= \mu e^X dt + \sigma e^X dW = \mu \$ dt + \sigma \$ dW$$

Plan: 1) Recall of ODE and proba.

2) Brownian motion

3) Stochastic integral + Itô's formula

4) SDE

5) Numerical analysis for SDE

ODE: $\begin{cases} y(t) = f(t, y(t)) \\ y(t_0) = y_0 \end{cases}$ | let E be a Banach space, $D \subset E$ open and convex
 | let I be an interval of \mathbb{R} .

$f: I \times D \rightarrow E$, $y: I \rightarrow D$ is the solution of the system.
 We want to show existence and uniqueness of the solution for the system under proper hypothesis.

Def: $f: I \times D \rightarrow E$ is said to be globally Lipschitz for x if $\exists L > 0$ st.
 $\forall x_1, x_2 \in D, \forall t \in I$

$$\|f(t, x_1) - f(t, x_2)\|_E \leq L \|x_1 - x_2\|_E$$

Thm Let $X \subset E$ a closed subset of E . Let $F: X \rightarrow X$ be a contraction (ie $L < 1$), then $\exists! y \in X$ st $F(y) = y$.

Recall that we have $y(t) = y_0 + \int_{t_0}^t f(s, y(s)) ds$

Thm Assume $D = E$. Assume $f \in C(I \times D, E)$ be globally Lipschitz for x . Then $\forall y_0 \in D \exists! y \in C^1(I, D)$ st $\begin{cases} y'(t) = f(t, y(t)) \\ y(t_0) = y_0 \end{cases}$

Proof: Let us assume I closed and bounded. Let L be the Lipschitz constant of f .

Let $\mathcal{E} = (C(I, E), \|\cdot\|_{\mathcal{E}})$ with $\|y\|_{\mathcal{E}} = \max_{t \in I} e^{-2L|t-t_0|} \|y(t)\|_E$

$\|\cdot\|_{\mathcal{E}}$ is equivalent to $\|\cdot\|_{\infty}$ since, if we denote $T = \max_{t \in I} |t - t_0| > 0$ (since I closed and bounded)

$$\forall \|y\|_{\infty} = T \max_{t \in I} \|y(t)\|_E \leq \max_{t \in I} e^{-2L|t-t_0|} \|y(t)\|_E \leq \max_{t \in I} \|y(t)\|_E = \|y\|_{\infty}$$

\mathcal{E} is complete since I is compact.

let us define $T: \mathcal{E} \rightarrow \mathcal{E}$ with $\forall t \in I$

$$(Ty)(t) = y_0 + \int_{t_0}^t f(s, y(s)) ds$$

It is clear that $Ty \in \mathcal{E}$ since f is continuous. Assume $t > t_0$

$$\begin{aligned} \|Ty_1(t) - Ty_2(t)\|_E &\leq \left\| \int_{t_0}^t f(s, \gamma_1(s)) - f(s, \gamma_2(s)) ds \right\|_E \\ &\leq \int_{t_0}^t \|f(s, \gamma_1(s)) - f(s, \gamma_2(s))\|_E ds \\ &\leq \int_{t_0}^t L \|\gamma_1(s) - \gamma_2(s)\|_E ds \\ &= \int_{t_0}^t L e^{2L|s-t_0|} e^{-2L|s-t_0|} \|\gamma_1(s) - \gamma_2(s)\|_E ds \end{aligned}$$

$$\leq \int_{t_0}^t L e^{2L|s-t_0|} \max_{t \in I} \|y_1 - y_2\|_{\Sigma} e^{-2L|t-t_0|} ds$$

$$\leq \int_{t_0}^t L e^{2L|s-t_0|} \|y_1 - y_2\|_{\Sigma} ds = \|y_1 - y_2\|_{\Sigma} L \int_{t_0}^t e^{2L|s-t_0|} ds \leq$$

$$\leq \frac{1}{2} e^{2L|t-t_0|} \|y_1 - y_2\|_{\Sigma}$$

$$\Rightarrow \|Ty_1 - Ty_2\|_{\Sigma} \leq \frac{1}{2} \|y_1 - y_2\|_{\Sigma}$$

$\Rightarrow T$ is a contraction from Σ to Σ

$\Rightarrow \exists ! y \in \Sigma$ st $y = Ty = T^2 y = \dots$

$$= \int_{t_0}^t \begin{cases} \frac{e^{2L(s-t_0)}}{2L} \Big|_{t_0}^t & \text{if } t > t_0 \\ \frac{e^{2L(t_0-s)}}{-2L} \Big|_{t_0}^t & \text{if } t < t_0 \end{cases} ds$$

$$= \begin{cases} \frac{e^{2L(t-t_0)}}{2L} - \frac{1}{2L} < \frac{e}{2L} \\ \frac{1}{2L} + \frac{e^{2L(t_0-t)}}{2L} \leq \frac{e^{2L|t-t_0|}}{2L} \end{cases}$$

Assume I either not closed or not bounded.

Then $I = \bigcup_{n \in \mathbb{N}} I_n$ with $I_n \subset I_{n+1}$, I_n bounded and closed

Let γ_n be the solution on I_n . By unicity, $\gamma_{n+1}|_{I_n} = \gamma_n$

Then γ_n 's define st $y = \gamma_n$ on I_n

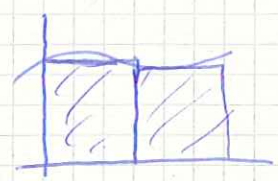
This imply unicity and existence of the solution. □

Numerical methods for ODE:

We want to approximate the solution of $\begin{cases} y'(t) = f(t, y(t)) \\ y(t_0) = y_0 \end{cases}$, i.e. $y(t) = y_0 + \int_{t_0}^t f(s, y(s)) ds$

Let $T > 0$, $N \in \mathbb{N}$, $h = \frac{T}{N}$, $t_n = t_0 + n \cdot h$

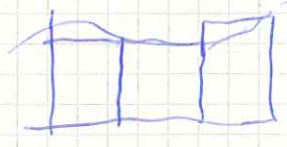
Euler explicit: $y_{n+1} = y_n + h f(t_n, y_n)$



This is explicit can be seen as an approximation of $\int_{t_n}^{t_{n+1}} f(s, y(s)) ds \approx h f(t_n, y(t_n))$

Euler implicit: $y_{n+1} = y_n + h f(t_{n+1}, y_{n+1})$

That is $\int_{t_n}^{t_{n+1}} f(s, y(s)) ds \approx h f(t_{n+1}, y(t_{n+1}))$



Let We say a method has order p if $\|y(h) - y_0\|_{\Sigma} \leq O(h^{p+1}) \forall f$ suff. smooth

Example

Euler explicit: $y_1 - (y(t_0) + h y'(t_0) + O(h^2)) = y_1 - (y_0 + h f(t_0, y_0) + O(h^2)) = O(h^2)$

Probability:

Definitions: (Ω, \mathcal{U}, P) : probability space

Ω is the universe, domain, $\omega \in \Omega$ is a sample point.

\mathcal{U} is a σ -algebra and represent the information. $A \in \mathcal{U}$ is an event.

P is the probability, a measure with respect to (Ω, \mathcal{U}) and $(\mathbb{R}, \mathcal{B}, \mathcal{B})$

of σ -algebra is a collection \mathcal{U} of subsets of Ω st

- $\emptyset, \Omega \in \mathcal{U}$

- $A \in \mathcal{U} \Rightarrow A^c \in \mathcal{U}$

- $A_1, A_2, \dots \in \mathcal{U} \Rightarrow \bigcup_{k=1}^{\infty} A_k, \bigcap_{k=1}^{\infty} A_k \in \mathcal{U}$

o) $P: \mathcal{U} \rightarrow [0, 1]$ is such that : i) $P(\emptyset) = 0, P(\Omega) = 1$

(we say $A \perp B, A, B$ indep if $P(A \cap B) = P(A)P(B)$)

$X_i: \Omega \rightarrow \mathbb{R}$ c.v. $\forall B_k \in \mathcal{B}_{\mathbb{R}}$ $P(X_1 \in B_1, \dots, X_n \in B_n) = P(X_1 \in B_1) \dots P(X_n \in B_n)$

ii) $P(\bigcup_{k=1}^{\infty} A_k) \leq \sum_{k=1}^{\infty} P(A_k)$

$P(\bigcap_{k=1}^{\infty} A_k) = \sum_{k=1}^{\infty} P(A_k)$

o) A property which holds ~~for all~~ except for A with $P(A) = 0$ hold almost surely

o) The Borel σ -algebra of \mathbb{R}^n is the smallest σ -alg \mathcal{B} that contains all open sets of \mathbb{R}^n .

o) $X: \Omega \rightarrow \mathbb{R}^n$ is an n-dimensional random variable ^(r.v.) if $\forall B \in \mathcal{B}$

$X^{-1}(B) \in \mathcal{U}$. $X: \Omega \rightarrow \mathbb{R}^n$ is an n-dimensional random vector X_i is c.v.

$\mathcal{U}(X) := \{X^{-1}(B) \mid B \in \mathcal{B}\}$ is the σ -alg generated by X (Lemma)

$\mathcal{U}(X)$ contains all the relevant information about X .

Examples: $\Omega = \{ \square, \square, \square, \square, \square, \square \} = \{1, \dots, 6\}$

$\mathcal{U} = \{ \text{all subsets of } \Omega \}$

$P(A) = \frac{|A|}{6} \quad \forall A \in \mathcal{U}$

$X(\omega) = \begin{cases} 0 & \text{if } \omega \in \{1, 2\} \\ 1 & \text{if } \omega \in \{3, 4, 5, 6\} \end{cases}$

$\mathcal{U}(X) = \{ \emptyset, \{1, 2\}, \{3, 4, 5, 6\}, \Omega \}$

$X(\omega) = \begin{cases} n & \text{if } \omega = n \end{cases}$

$\mathcal{U}(X) = \mathcal{U}$

Def: i) The distribution function of X is $F_X: \mathbb{R}^n \rightarrow [0, 1]$ st

$F_X(x) = P(X \leq x)$

$\forall x \in \mathbb{R}^n$

(ii) $X_1, \dots, X_m: \Omega \rightarrow \mathbb{R}^n$ r.v., their joint distribution function is F_{X_1, \dots, X_m} st $F_{X_1, \dots, X_m}(x_1, \dots, x_m) = P(X_1 \leq x_1, \dots, X_m \leq x_m)$

• A density function for X is a nonnegative, integrable function $f: \mathbb{R}^n \rightarrow \mathbb{R}$

st. $F(x) = F(x_1, \dots, x_n) = \int_{-\infty}^{x_1} \dots \int_{-\infty}^{x_n} f(y_1, \dots, y_n) dy_1 \dots dy_n$

• The expected value of X is:

$E(X) = \int X dP = \int_{\mathbb{R}^n} x f(x) dx$, $E(XY) = E(X)E(Y)$ if $X \perp Y$
(and $E(X) < \infty, E(Y) < \infty$)

• The variance of X is

$V(X) = \int_{\mathbb{R}^n} [X - E(X)]^2 dP = E(X^2) - [E(X)]^2$ $V(X+Y) = V(X) + V(Y)$
 $= \int_{\mathbb{R}^n} |x - m|^2 f(x) dx$

• The covariance of X, Y is $Cov(X, Y) = E(XY) - E(X)E(Y)$ Remark $Cov(X, X) = Var(X)$

• X is iid if $X_i \perp X_j$ and X_i has law μ
Example: $X: \Omega \rightarrow \mathbb{R}$ has Gaussian law if its density $f(x) = \frac{1}{\sqrt{2\pi\sigma^2}} e^{-\frac{(x-m)^2}{2\sigma^2}}$ with mean m and variance σ^2

We write $X \sim N(m, \sigma^2)$

$E(X) = \int_{\mathbb{R}} x f(x) dx = \frac{1}{\sqrt{2\pi\sigma^2}} \int_{\mathbb{R}} (m+x-m) e^{-\frac{(x-m)^2}{2\sigma^2}} dx = m + \underbrace{\int_{\mathbb{R}} x f(x) dx}_{=0} = m$

• $X: \Omega \rightarrow \mathbb{R}^n$ has gaussian law if $a \cdot X$ has gaussian law $\forall a \in \mathbb{R}^n$
This implies $f(x) = \frac{1}{(2\pi)^{n/2} \det(\Gamma)^{1/2}} e^{-\frac{1}{2}(x-m)^T \Gamma^{-1}(x-m)}$

with $(C_{ij}) = Cov(X_i, X_j)$

The (central limit) X_1, \dots, X_n, \dots iid. $E(X_i) = m, V(X_i) = \sigma^2 > 0$

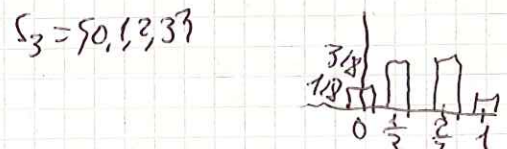
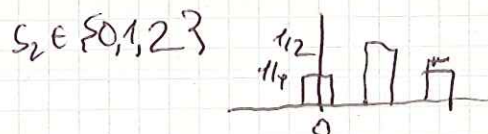
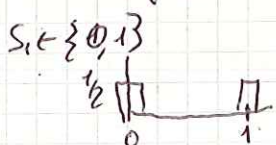
$S_n = X_1 + \dots + X_n$

Then $\forall a, b$ $-\infty < a < b < \infty$, $\frac{\sqrt{n}}{\sigma} \cdot \left[\frac{X_1 + \dots + X_n}{n} - m \right] \xrightarrow{L} N(0, 1)$

ie. $\frac{X_1 + \dots + X_n}{n} \sim N(m, \frac{\sigma^2}{n})$

Ex. $x_n \sim b(\frac{1}{2})$: $X \sim b(\frac{1}{2})$: $P(X_n=0) = \frac{1}{2} = P(X_n=1)$ $\rightarrow X(0) = 0, X(1) = 1$
 $S_n = X_1 + \dots + X_n \sim B(n, \frac{1}{2})$ $E(X) = \frac{0+1}{2}, Var(X) = \frac{1}{2} - \frac{1}{4} = \frac{1}{4}$

$\frac{\sqrt{n}}{1/2} \left(\frac{S_n}{n} - \frac{1}{2} \right) \xrightarrow{L} N(0, 1)$, $\frac{S_n}{n} \sim N\left(\frac{1}{2}, \frac{1}{4n}\right)$



Def: Stochastic process: $X = (\Omega, \mathcal{F}, (\mathcal{F}_t)_{t \in T}, (X_t)_{t \in T}, \mathbb{P})$

Ω : universe, domain
 \mathcal{F} : σ -algs
 \mathbb{P} : probs

$(\Omega, \mathcal{F}, \mathbb{P})$ a probabilistic space

$\mathcal{F}_t \subset \mathcal{F}$ is the filtration; $\mathcal{F}_t = \bigcup_{s \leq t} \mathcal{X}_s = \mathcal{F}_{t_1} \subset \mathcal{F}_{t_2}$ $t_1 \leq t_2$: information at time t .

T is the index set: $\mathbb{N}, \mathbb{Z}, \mathbb{R}, [0, 1], \mathbb{T}$: torus, a manifold, etc.

Example: gaussian stochastic process: $\forall t_1, \dots, t_n \in T, T = [0, \infty]$

$(X_{t_1}, \dots, X_{t_n})$ has gaussian law with $m(t) = \mathbb{E}(X_t)$ and
 $\text{Cov}(X_s, X_t) = \mathbb{E}[(X_s - m(s))(X_t - m(t))] = \text{Cov}(X_t, X_s)$

Ex $T = \mathbb{N}$ discrete

$$\begin{cases} X_{n+1} = X_n + \beta_{n+1} \\ X_0 = 0 \end{cases}$$

$\beta_n \sim N(0, 1)$ and β_n iid

$$\Rightarrow X_n = \sum_{j=1}^n \beta_j$$

$\Rightarrow X$ is Gaussian since $\forall n, (X_i)_{i=1}^n$ has gaussian law:

$$\sum_{i=1}^n a_i X_i = \sum_{i=1}^n a_i \left(\sum_{j=1}^i \beta_j \right) = \sum_{j=1}^n b_j \beta_j \sim \mathcal{N}\left(0, \sum_{i=1}^n b_i^2\right)$$

$$\mathbb{E}(X_n) = 0 \quad \text{since } \beta_i \sim \mathcal{N}(0, 1) \sim \mathcal{N}(0, 1^2)$$

$$\text{Cov}(X_n, X_m) = \sum_{i=1}^n \sum_{j=1}^m \underbrace{\text{Cov}(\beta_{j_1}, \beta_{j_2})}_{\delta_{j_1, j_2}} = \min(n, m)$$

$$\boxed{\text{Cov}(X_n, X_m) = \min(n, m)}$$

$$X \sim \mathcal{N}(m, \sigma^2)$$

$$aX \sim \mathcal{N}(a m, a^2 \sigma^2)$$

2. BROWNIAN MOTION (B.M.)

1. HISTORICAL INTRODUCTION

1827 Scottish botanist ROBERT BROWN observed the erratic behavior of tiny particles ejected from pollen grains suspended in water. Today, we explain this phenomenon by random collisions of surrounding molecules against the observed pollen grains.

1905 ALBERT EINSTEIN published the article at the foundation of modern brownian motion. We are going to study its physical origins to understand the meaning of the mathematical definition that we will give later.

2. INTERPRETATION of B.M. as DIFFUSION PROCESS

- Consider a long thin tube filled with some fluid at rest, and tiny particles that move inside it (e.g., ink particles).
- Let $f(x, t)$ be the particle density at time t in the point x . We consider 1D spatial motion to simplify.
- We set $P_x(y, \tau)$ the PROBABILITY DENSITY FUNCTION that a particle placed at x moves to $x+y$ in a time τ .

We get then:

$$f(x, t+\tau) = \int_{-\infty}^{+\infty} f(x-y, t) P_x(y, \tau) dy$$

INCREMENT IN PARTICLE POSITION IS REGARDED AS A RANDOM VARIABLE
CHANGE IN PARTICLE DENSITY

- Taking a Taylor series of $f(x-y, t)$:

$$f(x, t+\tau) = f(x, t) \underbrace{\int_{-\infty}^{+\infty} P_x(y, \tau) dy}_{=1, \text{ because it is a pdf}} + \frac{\partial f}{\partial x}(x, t) \underbrace{\int_{-\infty}^{+\infty} -y P_x(y, \tau) dy}_{\text{by symmetry, } P_x(y, \tau) = P_x(-y, \tau)} + \frac{1}{2} \frac{\partial^2 f}{\partial x^2}(x, t) \int_{-\infty}^{+\infty} y^2 P_x(y, \tau) dy + \dots$$

- So we are left with:

$$f(x, t+\tau) = f(x, t) + \frac{1}{2} \frac{\partial^2 f}{\partial x^2}(x, t) \int_{-\infty}^{+\infty} y^2 P_x(y, \tau) dy + \dots$$

$$\lim_{\tau \rightarrow 0} \left(\frac{f(x, t+\tau) - f(x, t)}{\tau} \right) = \frac{1}{2} \frac{\partial^2 f}{\partial x^2}(x, t) \times \lim_{\tau \rightarrow 0} \int_{-\infty}^{+\infty} y^2 \frac{S_x(y, \tau)}{\tau} dy$$

Assumptions: (i) The other terms of the Taylor expansion are negligible;
(ii) The limit on the RHS exists finite & we denote its value by D .

• We get:

$$\frac{\partial f}{\partial t}(x, t) = \frac{D}{2} \frac{\partial^2 f}{\partial x^2}(x, t), \text{ which is a } \underline{\text{DIFFUSION EQUATION!}}$$

Its solution is: $f(x, t) = \frac{1}{\sqrt{2\pi Dt}} e^{-\frac{x^2}{2Dt}}$.

• WE DEDUCE THAT THE PARTICLE DENSITY $f(x, t)$ IS THE PROBABILITY DENSITY FUNCTION OF A RANDOM VARIABLE WHICH FOLLOWS A NORMAL DISTRIBUTION $N(0, Dt)$!
(According to these observations, we define our B.M. as follows:)

3. DEFINITION of B.M.

A Stochastic process W is called BROWNIAN MOTION (or Wiener process) if:

- $W(0) = 0$;
- $\forall 0 \leq s \leq t, W(t) - W(s) \sim N(0, t-s)$; (THE INCREMENTS FOLLOW A NORMAL DISTRIBUTION)
- $\forall 0 < t_1 < t_2 < \dots < t_m$, The increments $W(t_1), W(t_2) - W(t_1), \dots, W(t_m) - W(t_{m-1})$ are independent.

SIMULATION? plot-BM.m

RK (i) Another physical observation: A B.M. DOES NOT DEPEND ON ITS PAST, IT EVOLVES RANDOMLY. If we zoom on a B.M. and change the origin of our reference system, we find another B.M..

(ii) B.M. IS AN EXISTING OBJECT. To build one, we can take an ORTHONORMAL BASIS of L^2 (e.g. built upon Haar wavelets), then study series whose terms are these "primitives" multiplied by random variables. One can check that we get a B.M. under certain hypotheses...

The first explicit construction of this type is due to N. Wiener.

4. CONSTRUCTION of B.M.

- LET $(Y_j)_{j \in \mathbb{N}}$ BE A SEQUENCE OF I.I.D. RANDOM VARIABLES, $N(0,1)$.
- N. WIENER SHOWED THAT THE PROCESS $W = (W_t)_{t \in [0, \pi]}$ DEFINED BY:

$$W_t = \frac{t}{\sqrt{\pi}} Y_0 + \sum_{n \geq 1} \left(\sum_{j=2^{n-1}}^{2^n-1} \sqrt{\frac{2}{\pi}} \frac{\sin(jt)}{j} Y_j \right)$$

IS A BROWNIAN MOTION ON $I = [0, \pi]$.

- BASIS of $L^2([0, \pi])$: $e_0(t) = \frac{1}{\sqrt{\pi}}$, $e_{j_n}(t) = \sqrt{\frac{2}{\pi}} \cos(j_n t)$
(EXPANSION of WHITE NOISE IN THIS BASIS) ($j_n \geq 1$)

By formally deriving:

$$\dot{W}_t = \frac{dW}{dt}(t) = \frac{1}{\sqrt{\pi}} Y_0 + \sum_{n \geq 1} \underbrace{\left(\sum_{j=2^{n-1}}^{2^n-1} \sqrt{\frac{2}{\pi}} \cos(jt) \frac{Y_j}{j} \right)}_{\text{divergent series almost everywhere}} \quad \xrightarrow{\text{WHITE NOISE}}$$

┌ This example of Wiener was also the starting point of the theory of RANDOM FOURIER SERIES. ┘

RT: Recall from Guillaume's talk that the formal time derivative $\dot{W}(t) = \xi(t)$ is "1D white noise". (SAMPLE POINT) $\rightarrow \omega \in \Omega, \leftarrow$ UNIVERSE
However, we will see later, for almost every ω , the sample path $t \mapsto W(t, \omega)$ is in fact differentiable for no time $t \geq 0$. Thus $\dot{W}(t) = \xi(t)$ does not really exist.

5. B.M. IS A CENTERED GAUSSIAN PROCESS

Guillaume has already defined what is a Gaussian process.

Def. $(X(t))_{t \in I}$, real process, is called Gaussian if $\forall k \geq 1$,
and $t_1, \dots, t_k \in I$, $(X(t_1), \dots, X(t_k))$ is a Gaussian R.V.

Def. $(X(t))_{t \in I}$, real process, is centered if, $\forall t \in I$, $\mathbb{E}(X(t)) = 0$.

LEMMA. Suppose $W(t)$ is a (1D) B.M. Then:

(i) W is a centered Gaussian process

(eq. (6), p. 43)

$$\mathbb{E}(W(t)) = 0, \quad \mathbb{E}(W^2(t)) = t, \quad (t \geq 0)$$

(ii) Moreover, $\mathbb{E}(W(t)W(s)) = \min\{s, t\}$, $(t, s \geq 0)$.

cf. $\text{cov}(X, Y) = \mathbb{E}(XY) - \mathbb{E}(X)\mathbb{E}(Y) = 0$ (Guillaume's)

Proof. (i) is immediate from the def. of B.M., since $W(t)$ is $\mathcal{N}(0, t)$.

(ii) Assume $t \geq s \geq 0$. Then

$$\mathbb{E}(W(s)W(t)) = \mathbb{E}((W(s) + W(t) - W(s))W(s))$$

$$= \underbrace{\mathbb{E}(W(s)^2)}_{W(s) \text{ is } \mathcal{N}(0, s)} + \underbrace{\mathbb{E}((W(t) - W(s))W(s))}_{W(t) - W(s) \text{ is indep. of } W(s) \text{ (because of def. of B.M.)}}$$

$$= s + \underbrace{\mathbb{E}(W(t) - W(s))}_{= 0} \underbrace{\mathbb{E}(W(s))}_{= 0}$$

$$= s = \min\{s, t\}.$$

because they are centered

□

4 6. SAMPLE PATH PROPERTIES: (p. 53 Evans)

orally We'll show that, for almost every ω , the SAMPLE PATH $t \mapsto W(t, \omega)$ is uniformly Hölder continuous for each exponent $0 < \gamma < \frac{1}{2}$, but nowhere Hölder continuous with any exponent $\gamma > \frac{1}{2}$.

Def. (uniformly Hölder continuous)

Let $0 < \gamma \leq 1$. A function $f: [0, T] \rightarrow \mathbb{R}$ is called uniformly Hölder continuous with exponent $\gamma > 0$ if there exists a constant K s.t.

$$|f(t) - f(s)| \leq K |t - s|^\gamma \quad \forall s, t \in [0, T]$$

NB: $\gamma = 1$ Lipschitz continuity

SIMULATION?

NO.

\rightarrow differentiable almost everywhere (Chain of inclusions)

Thm. (continuity of Brownian sample paths) [p. 16R in bass.]

For almost all ω and any $T > 0$, the sample path $t \mapsto W(t, \omega)$ is uniformly Hölder continuous on $[0, T]$ for each exponent $0 < \gamma < \frac{1}{2}$.

~~* Proof (ii) ideas of proof are better~~

[p. 54 Evans, also Gilles p. 18R-19]

NOWHERE DIFFERENTIABILITY. Sample paths of Brownian motion are with probability one nowhere Hölder continuous with exponent $\gamma > \frac{1}{2}$, and thus are nowhere differentiable.

Thm. (i) For each $\frac{1}{2} < \gamma \leq 1$ and almost every ω , $t \mapsto W(t, \omega)$ is nowhere Hölder continuous with exponent γ . $(\mathbb{P}(\exists W \in C^\gamma([0, T])) = 0$ for $\gamma > \frac{1}{2}$)

(ii) In particular, for a.e. ω , the sample path $t \mapsto W(t, \omega)$ is nowhere differentiable.

Proof (THE POINTS?) ~~HARDOV PROPERTY?~~ $(\mathbb{P}(\exists W \in BV([0, T])) = 0)$

3. STOCHASTIC INTEGRALS (dovrebbe durare un'ora)

Remember what we want to do: WE WANT TO DEVELOP A THEORY of STOCHASTIC DIFFERENTIAL EQUATIONS of THE FORM

$$\begin{cases} dx = b(x,t) dt + B(x,t) dW \\ X(0) = X_0, \end{cases}$$

which we will interpret to mean:

$$(*) \quad X(t) = X_0 + \int_0^t b(x,\alpha) d\alpha + \int_0^t B(x,\alpha) dW$$

$\forall t \geq 0.$

← We must first DEFINE STOCHASTIC INTEGRALS of THE FORM:

$$\int_0^T G(\alpha) dW(\alpha)$$

for some wide class of stochastic processes G . (then the RHS of (*) at least make sense).

But the expression " $\int_0^T G(\alpha) dW(\alpha)$ " simply cannot be understood as an ordinary integral.

4.1.2.1. Riemann sums.

What might be our appropriate definition for $\int_0^T W dW =$ (where $W(\cdot)$ is a one dimensional B.M.)

A reasonable procedure is to construct a Riemann sum approximation and then - if possible - to pass to limits.

~~We start by considering $g(x,t) = \sum_{k=0}^n g_k(x) \mathbb{1}_{]t_k, t_{k+1}]}(t)$, $t \in [0, T]$~~

~~g_k random variables~~

~~P.66, 4.2.2~~

~~$0 < t_1 < \dots < t_n = T$ partition of $[0, T]$~~

~~WE SET $\int_0^T g(\alpha) dW(\alpha) := \sum_{k=0}^{n-1} g_k (W(t_{k+1}) - W(t_k))$~~

~~This is the \int_0^T stochastic integral of G on the interval $(0, T)$. (*)~~

DEF.

(i) $[0, T]$ interval, partition P of $[0, T]$ is
 $P := \{0 = t_0 < t_1 < \dots < t_m = T\}$.

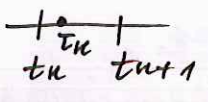
(ii) mesh size of P is
 $|P| := \max_{0 \leq k \leq m-1} |t_{k+1} - t_k|$.

(iii) For fixed $0 \leq \lambda \leq 1$ and P , set

$t_k := (1-\lambda)t_k + \lambda t_{k+1} \quad (k = 0, \dots, m-1)$
(PARAMETERIZED SEGMENT: t_k IS A POINT LYING WITHIN THE SUBINTERVAL $[t_k, t_{k+1}]$.)

DEF. For P & $0 \leq \lambda \leq 1$, we write

$R = R(P, \lambda) := \sum_{k=0}^{m-1} W(t_k) (W(t_{k+1}) - W(t_k))$



(This is the Riemann sum approximation of $\int_0^T W dW$.)

I will not talk about this in this minicourse, but different choices of λ lead to different definitions of the Itô stochastic integral. $\lambda = 0$ ITÔ $\lambda = 1/2$ STRATONOVICH.

Q: What happens when $|P| \rightarrow 0$, with λ fixed?

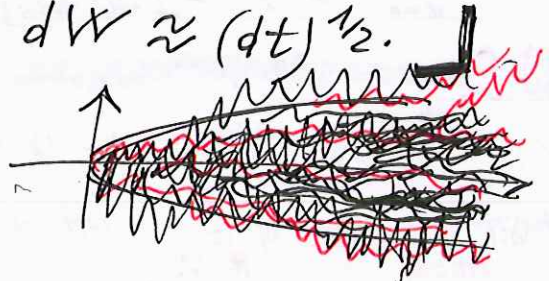
LEMMA (quadratic variation). Let $[a, b]$ be an interval in $[0, \infty)$, and suppose

$P_n := \{a = t_0^{(n)} < t_1^{(n)} < \dots < t_{m_n}^{(n)} = b\}$

are partitions of $[a, b]$, with $|P_n| \rightarrow 0$ as $n \rightarrow \infty$.

Then $\sum_{k=0}^{m_n-1} (W(t_{k+1}^{(n)}) - W(t_k^{(n)}))^2 \rightarrow (b-a)$ in $L^2(\Omega)$,
as $n \rightarrow \infty$. (length of the interval)

Rk. This result partly justifies the heuristic idea that $dW \approx (dt)^{1/2}$.



SIMULATION
Plot-BM.m
MAYBE STOP WORKS??

4.2 [p. 65 EVANS] 2. Itô's Integral

5 ter

Let $W(\cdot)$ be a 1D B.M. defined on some probability space $(\Omega, \mathcal{U}, \mathbb{P})$.

Informal def 1 (idea)

(w.r.t. $W(\cdot)$)

$\mathcal{F}(\cdot)$, family of σ -algebras, called nonanticipating \mathcal{F} (or filtration) if $\mathcal{F}(t)$ "contains all information available to us at time t ", but not the information after t ."

Informal def 2 A real-valued stoch. process $G(\cdot)$ is

called NONANTICIPATING (w.r.t. $\mathcal{F}(\cdot)$) if for each time $t \geq 0$, $G(t)$ is $\mathcal{F}(t)$ -measurable.

(idea: " $\forall t \geq 0$, the R.V. $G(t)$ depends upon only the information available in the σ -algebra $\mathcal{F}(t)$."

STRONGER NOTION progressively measurable stochastic processes.

THE IDEA IS THAT $G(\cdot)$ IS NONANTICIPATING AND, IN ADDITION, IS JOINTLY MEASURABLE IN THE VARIABLES t AND ω TOGETHER.

INFORMAL DISCUSSION OF NONANTICIPATING PROCESSES

ORALLY

Idea: for progressively measurable processes, we can define, understand, the Itô stochastic integral $\int_0^T G dW$ in terms of useful and elegant formulas.

Def. (i) $\mathbb{L}^2(0, T)$ denote the space of all real-valued, ~~nonanticipating~~ "progressively measurable" stochastic processes $G(\cdot)$ s.t. $\mathbb{E}(\int_0^T G^2 dt) < \infty$.

(ii) $\mathbb{L}^1(0, T)$ $\dots \dots \dots$ \mathbb{R} , s.t. $\mathbb{E}(\int_0^T |G| dt) < \infty$.

(4.2.2.)

STEP PROCESSES. A process $G \in \mathbb{L}^2(0, T)$ is called a STEP PROCESS

if \exists partition $\mathcal{P} = \{0 = t_0 < t_1 < \dots < t_m = T\}$ of $[0, T]$ s.t.

$G(t) \equiv G_k$ for $t_k \leq t < t_{k+1}$ ($k=0, \dots, m-1$):

R.V. $G(\omega, t) = \sum_{k=0}^{m-1} G_k(\omega) \mathbb{1}_{]t_k, t_{k+1}]}(t), t \in [0, T], \omega \in \Omega$

DRAWING NOW

DEF. Let $G \in \mathbb{L}^2(0, T)$. ~~we SET~~ we SET

$\int_0^T G dW := \sum_{k=0}^{m-1} G_k (W(t_{k+1}) - W(t_k))$

THIS IS THE ITÔ'S STOCHASTIC INTEGRAL OF G ON THE INTERVAL $(0, T)$.

(NOTE CAREFULLY THAT THIS INTEGRAL IS A R.V.)

⊛ We denote by \mathcal{E} the set of step processes:

$$\mathcal{E} = \{ \text{step processes} \}.$$

$\mathbb{L}^2(0, T)$ For $X, Y \in \mathbb{L}^2(0, T)$, let us define the distance function: $d_{\mathbb{L}^2}(X, Y) := \mathbb{E} \left[\int_0^T |X - Y|^2 dt \right]$.

$(\mathbb{L}^2, d_{\mathbb{L}^2})$ is a complete metric space.

(APPROXIMATION BY STEP PROCESSES)

"LEMMA" The set \mathcal{E} of step processes is dense in $(\mathbb{L}^2, d_{\mathbb{L}^2})$, i.e., there exists a sequence of step processes that converges to an element G of $\mathbb{L}^2(0, T)$: $(G_m)_{m \in \mathbb{N}} \in \mathcal{E}$
(this is the same as lemma p. 68 Evans)

$$d_{\mathbb{L}^2}(G, G_m) \xrightarrow{m \rightarrow \infty} 0.$$

(LEMMA p.66 IN BASSO).

LEMMA Assume that g_k is independent of $\{W(t_{l+1}) - W(t_l); l \geq k\}$

Mean:
$$\mathbb{E} \left(\int_0^T g(s) dW(s) \right) \stackrel{\text{using } \otimes}{=} \sum_{k=0}^{m-1} \mathbb{E} \left(g_k (W(t_{k+1}) - W(t_k)) \right)$$

indep. hp. \downarrow

$$= \sum_{k=0}^{m-1} \mathbb{E}(g_k) \mathbb{E}(W(t_{k+1}) - W(t_k)) \stackrel{\text{By def. of B.M.}}{=} 0$$

Variance:
$$\mathbb{E} \left(\left(\int_0^T g(s) dW(s) \right)^2 \right) = \sum_{k,l=0}^{m-1} \mathbb{E} \left(g_k g_l (W(t_{k+1}) - W(t_k)) (W(t_{l+1}) - W(t_l)) \right)$$

$$= \sum_{k=0}^{m-1} \mathbb{E} \left(g_k^2 (W(t_{k+1}) - W(t_k))^2 \right) + 2 \sum_{k < l} \mathbb{E} \left(g_k g_l (W(t_{k+1}) - W(t_k)) (W(t_{l+1}) - W(t_l)) \right)$$

(Gaussian Process)
 $\mathbb{E}((W_k - W_l)^2) = t - s$

THIS TERM IS INDEPENDENT of $g_k g_l (W(t_{k+1}) - W(t_k))$

indep. $\Rightarrow \sum_{k=0}^{m-1} \mathbb{E}(g_k^2) (t_{k+1} - t_k) + 2 \sum_{k < l} \mathbb{E}(g_k g_l (W(t_{k+1}) - W(t_k))) \underbrace{\mathbb{E}(W(t_{l+1}) - W(t_l))}_{=0}$

$$= \int_0^T \mathbb{E}(g(s)^2) ds$$

(By def of B.M.)
* We actually "built" "have" an isometry for the stochastic integral.

THE PLAN NOW IS TO APPROXIMATE AN ARBITRARY PROCESS $G \in \mathbb{L}^2(0,T)$ BY STEP PROCESSES IN $\mathbb{L}^2(0,T)$ AND THEN PASS TO LIMITS TO DEFINE THE ITO INTEGRAL OF G .

P.68 LEMMA (Approximation by step processes). If $G \in \mathbb{L}^2(0,T)$, there exists a sequence $(G_n)_{n \in \mathbb{N}}$ of bounded step processes $G_n \in \mathbb{L}^2(0,T)$ such that

$$\mathbb{E} \left(\int_0^T |G - G_n|^2 dt \right) \rightarrow 0$$

(This is exactly what I defined as distance $d_{\mathbb{L}^2}(G, G_n) \rightarrow 0$)

(dense)
distance de cet espace

Space of all real-valued, progressively measurable stochastic processes s, t .
 $\mathbb{E} \left(\int_0^T G^2 dt \right) < \infty$

(4.3) 3. ITO'S CHAIN & PRODUCT RULE

9

Def. Suppose that $X(\cdot)$ is a real-valued stochastic process satisfying

$$X(r) = X(0) + \int_0^r F dt + \int_0^r G dW$$

for some $F \in \mathbb{L}^1(0, T)$, $G \in \mathbb{L}^2(0, T)$ and all times $0 \leq s \leq r \leq T$. We say that $X(\cdot)$ has the stochastic differential

$$dX = F dt + G dW, \quad \text{for } 0 \leq t \leq T.$$

ORALLY (NB) the symbols are simply an abbreviation for the integral expressions above; strictly speaking, "dX", "dt" and "dW" have NO MEANING ALONE.

Thm. Suppose that $X(\cdot)$ (real-valued stochastic process) has a stochastic differential

$$dX = F dt + G dW, \quad \begin{array}{l} (F, G \text{ processes} \\ F \in \mathbb{L}^1(0, T) \\ G \in \mathbb{L}^2(0, T). \end{array}$$

Let $\phi: \mathbb{R} \times [0, T] \rightarrow \mathbb{R}$, $\phi(x, t)$, $\phi \in \mathcal{C}^2$
(i.e., $\partial\phi/\partial t$, $\partial\phi/\partial x$, $\partial^2\phi/\partial x^2$ exist & are continuous).

Then $\phi(X(t), t)$ has the STOCHASTIC DIFFERENTIAL:

$$\begin{aligned} d\phi(X, t) &= \phi_t dt + \phi_x dX + \frac{1}{2} \phi_{xx} G^2 dt \\ &= (\phi_t + \phi_x F + \frac{1}{2} \phi_{xx} G^2) dt + \phi_x G dW. \end{aligned}$$

(this is called ITO'S CHAIN RULE or ITO'S FORMULA).

(Remark: ϕ_x, ϕ_t , etc., above is $(X(t), t)$).

EXAMPLES/ILLUSTRATIONS of ITO'S CHAIN RULE.

Ex. 1) ~~Let~~ $X(\cdot) = W(\cdot)$, $\phi(x) = x^m$. LET US STUDY THE CASE ~~where~~ $(dX = dW)$ ~~and~~ thus
 $F \equiv 0, G \equiv 1$. Hence Ito's chain rule gives

$$d(W^m) = m W^{m-1} dW + \frac{1}{2} m(m-1) W^{m-2} dt.$$

So the particular case $m = 2$ reads:

$$d(W^2) = 2W dW + \underline{\underline{dt}}$$

(10)
see dropbox
SIMULATION OF THE INTEGRAL

↑ additional term of Itô

COMPARE WITH

~~$$d(W^2) = 2W dW$$~~

(see also p. 24 Gilles)

This integrated is the identity

$$2 \int_0^T W dW = W^2(T) - 1$$

EX 2

~~Another example of stochastic differential eq.~~

let's study another case: $dX = F dt + dW$

(This is example from pg. 24 of Gilles course; it coincides with the result of theorem p. 73-74 of Evans, taking $X_1 = X_2 = X$, $F_1 = F_2 = F$, $G_1 = G_2 = 1$.)

Then

$$d(X^2) = 2X dX + \underline{\underline{dt}}$$

ADDITIONAL TERM.

(PROOF IS QUITE LONG + 2 pages) NO PROOF.

~~$$\frac{d(X^2)}{dX} = 2X \quad d(X^2) = 2X dX$$~~

This is an instance of Itô's product rule:

Then (Itô's product rule) Suppose:

$$\begin{cases} dX_1 = F_1 dt + G_1 dW \\ dX_2 = F_2 dt + G_2 dW \end{cases} \quad (0 \leq t \leq T)$$

for $F_i \in \mathbb{H}^1(0, T)$, $G_i \in \mathbb{L}^2(0, T)$ ($i = 1, 2$). Then

$$d(X_1 X_2) = X_2 dX_1 + X_1 dX_2 + \underbrace{G_1 G_2 dt}_{\text{Itô's correction term}}$$

(Itô's product rule or Itô's formula).

This can be generalised to have more X_i

[END of MY PART]

II - EDS

idée: $x'(t) = f(t, x(t)) + g(t, x(t)) \frac{dw(t)}{dt}$

↳ formulation intégrale: $X(t) = X(0) + \int_0^t f(s, X(s)) ds + \int_0^t g(s, X(s)) dw(s)$ (*)

Pt. * a-t-il une solution?

c'est $f(s, \omega, X(s, \omega))$ me v.a. ...
we will forget it.

1) Existence et Unicité

Thm: $f: [0, T] \times \mathbb{R}^n \rightarrow \mathbb{R}^n$
 $g: [0, T] \times \mathbb{R}^n \rightarrow \mathcal{M}_{n, m}(\mathbb{R})$
 W brownian motion in \mathbb{R}^m .

- 1) $|f(t, x_1) - f(t, x_2)| \leq L |x_1 - x_2|$
- 2) $|g(t, x_1) - g(t, x_2)| \leq L |x_1 - x_2|$
- 3) $|f(t, x)| \leq L(1 + |x|)$
- 4) $|g(t, x)| \leq L(1 + |x|)$
- 5) $\mathbb{E}[|X_0|^2] < +\infty$.

Then $\exists! X \in \mathcal{L}^2([0, T])$ solution of (*).

Rq: unicity means if x_1, x_2 solutions \mathcal{P}^0 of (*) then
 $\mathbb{P}(X_1(t) = X_2(t), \forall t \in [0, T]) = 1$

idea proof: ^{density} X_1, X_2 solutions of (*) then

$$X_1(t) - X_2(t) = \int_0^t (f(s, X_1) - f(s, X_2)) ds + \int_0^t (g(s, X_1) - g(s, X_2)) dw(s)$$

$$\mathbb{E}[|X_1(t) - X_2(t)|^2] \leq 2 \times I + 2 \times II$$

$$I \leq \mathbb{E}\left[\left|\int_0^t f(s, X_1) - f(s, X_2) ds\right|^2\right]$$

$$\leq T \mathbb{E}\left[\int_0^t L^2 |f(s, X_1) - f(s, X_2)|^2 ds\right] \leq T L^2 \int_0^t \mathbb{E}[|X_1 - X_2|^2(s)] ds$$

CS

$$\mathbb{I} = \mathbb{E} \left[\left| \int_0^t (g(s, x_1) - g(s, x_2)) dW \right|^2 \right] \quad (2)$$

$$= \mathbb{E} \left[\int_0^t |g(s, x_1) - g(s, x_2)|^2 ds \right]$$

Indépendance

$$\leq L^2 \int_0^t \mathbb{E} [|x_1 - x_2|^2(s)] ds$$

$$\text{donc } \mathbb{E} [|x_1 - x_2|^2(t)] \leq C \int_0^t \mathbb{E} [|x_1 - x_2|^2(s)] ds$$

$$\text{cà d } \phi(t) \leq C \int_0^t \phi(s) ds$$

Grönwall!!!

$$\hookrightarrow \text{si } \phi(t) \leq K + \int_0^t R(s) \phi(s) ds$$

$$\text{alors } \phi(t) \leq K \exp\left(\int_0^t R(s) ds\right)$$

$$\text{donc ici } \underline{\phi(t) \leq 0}$$

$$\text{donc } \mathbb{E} [|x_1 - x_2|^2(t)] = 0 \quad \forall t$$

$$\text{"donc } x_1(t) = x_2(t) \text{ p.s., } \forall t \in [0, T]$$

On conclut "donc" x_1, x_2 p.s."

(b) Existence

$$\text{On pose } \begin{cases} X^0(t) = x_0 \\ X^{n+1}(t) = x_0 + \int_0^t f(s, X^n(s)) ds + \int_0^t g(s, X^n(s)) dW(s) \end{cases}$$

$$\text{On pose } d^n(t) = \mathbb{E} [|X^{n+1}(t) - X^n(t)|^2]$$

$$\text{Par récurrence, on montre que } d^n(t) \leq \frac{(Mt)^{n+1}}{(n+1)!} \text{ (cf inégalité que ci-dessous)}$$

Doat done abso

$$\mathbb{E} \left[\max_{0 \leq t \leq T} |X^{n+1} - X^n|^2(t) \right] \leq C \frac{(MT)^{n+1}}{(n+1)!}$$

Marbas done $IP(|X| > t) \leq \frac{\mathbb{E}[|X|]}{t}$

donc ici $IP \left(\max_{[0, T]} |X^{n+1}(t) - X^n(t)| > \frac{1}{2^n} \right) \leq 2^{2n} \frac{C(MT)^{n+1}}{(n+1)!}$

On $\sum_{n=1}^{+\infty} 2^{2n} \frac{(MT)^{n+1}}{(n+1)!} < +\infty$ donc Boel Cantelli conclut:

$$IP \left(\limsup_n \left\{ \max_{[0, T]} |X^{n+1}(t) - X^n(t)|^2 > \frac{1}{2^n} \right\} \right) = 0$$

ca'd $X^n = X^0 + \sum_{j=0}^{n-1} X^{j+1} - X^j$ CV uniform p.s. vers X.

On peut passer à la limite des ~~points on peut~~

$$X^T = X^0 + \int_0^T f(t, X^t(s)) ds + \int_0^T g(t, X^t(s)) dW(s)$$

et cela donne X solution de \otimes .

→ we have to check also $X \in \mathbb{L}^2$...

□

2) Explicitly solvable SDEs and examples → in general not solvable explicitly

ⓐ Linear SDEs

La solution de $dX = a(t)X dt + b(t)X dW$ est

$$X(t) = \exp \left(\int_0^t a(s) ds + \int_0^t b(s) dW(s) - \frac{1}{2} \int_0^t b(s)^2 ds \right) X_0$$

$Y(t)$

En effet, $dY(t) = a(t) dt + b(t) dW(t) - \frac{1}{2} b^2(t) dt$

$$\begin{aligned}
 \text{Let } dX(t) &= e^{Y(t)} X_0 dY(t) + \frac{1}{2} e^{Y(t)} X_0 f^2(t) dt \\
 &= \underbrace{e^{Y(t)} X_0}_{= X(t)} (a(t) dt + f(t) dW(t))
 \end{aligned}$$

OK

Ex: solution $dY = Y dW$ is $e^{W(t) - \frac{1}{2} t} Y(0)$.

Application: Black-Scholes model / Bachelier

S_t : price of ^{share} action at time t

$$\begin{cases}
 dS_t = \mu S_t dt + \sigma S_t dW_t \\
 S_0 = S_0
 \end{cases}$$

$\text{Can } \frac{dS_t}{S_t} = \underbrace{\mu dt}_{\text{drift of the price}} + \underbrace{\sigma dW_t}_{\text{volatility of share}}$
 relative change of action

$$E[S_t] = E[S_0] + \mu \int_0^t E[S_0] ds$$

$$\text{So } E[S_t] = \underbrace{e^{\mu t}}_{> 0} E[S_0]$$

numerical experiment.

(b) Brownian bridge

$B(0) = B(1) = 0$ and B looks like a Brownian motion.

$$\text{that is } P_A = \mathcal{L}(W_t | W_1 = 0), t \in [0, T]$$

$$\text{th} \begin{cases} dB(t) = -\frac{\beta}{1-t} dt + dW \\ B(0) = 0 \end{cases} \quad \text{marks} \quad (5)$$

$$\text{We ded} \quad B(t) = \exp\left(-\int_0^t \frac{1}{1-s} ds\right) \left(B(0) + \int_0^t \exp\left(\int_0^s \frac{1}{1-r} dr\right) dW(s) \right)$$

$$= (1-t) \int_0^t \frac{1}{1-s} dW_s$$

OPM $B(1) = 0$ p.s

Q $B(t) = W(t) - tW(1)$ marks.

(c) Stochastic oscillator

idea: $\ddot{X} = -\lambda^2 X + \frac{dW}{dt}$?

$$\begin{cases} dx = Y dt \\ dY = -\lambda^2 X dt + dW \end{cases}$$

Then if $Y_0 = 0$, $X(t) = X_0 \cos(\lambda t) + \frac{1}{\lambda} \int_0^t \sin(\lambda(t-s)) dW_s$

→ numerical experiment

(d) Molecular dynamic

A big particle ^(q, p) is submitted in a fluid to

- a potential V
- a friction force $-\gamma p$
- $\sqrt{\frac{2\gamma}{\beta}} dW$ collisions (as seen before)

$$\text{th} \begin{cases} dq = p dt \\ dp = (-\nabla V(q) - \gamma p) dt + \sqrt{\frac{2\gamma}{\beta}} dW \end{cases} \quad (\text{Langevin equation})$$

$\gamma \rightarrow +\infty$: friction term
acceleration $dq \rightarrow 0$

$$\text{the } \begin{cases} \alpha dq = p dt \\ 0 = (-\nabla V(q) - \partial p) dt + \sqrt{\frac{2\gamma}{\beta}} dW \end{cases}$$

$$\text{and } dq = -\gamma^{-1} \nabla V(q) dt + \sqrt{\frac{2}{\beta}} dW$$

$$\gamma \rightarrow +\infty : \left[\begin{aligned} dx &= -\nabla V(x) dt + \sigma dW \\ &\text{(overdamped limit)} \end{aligned} \right]$$

Simulation

ⓐ Stochastic Schrödinger

$$\begin{cases} i d\psi + \Delta \psi dt + |\mu|^{2\sigma} \psi dt = 0 \\ i d\psi + \Delta \psi \circ d\beta + |\mu|^{2\sigma} \psi dt = 0 \\ i d\psi + \Delta \psi dt + |\mu|^{2\sigma} \psi dt + g(\mu) dW = 0 \dots \end{cases}$$

V - Numerical Analysis of SDEs

1) Strong error

given W , I want X solution of $\begin{cases} dX = f(X) dt + g(X) dW \\ X(0) = X^0 \end{cases}$ As simply
↓

Euler-Maruyama method

T steps $T/N = h$

$$t_n = nh, \quad n = 0, \dots, N$$

Algorithm: $\begin{cases} X_0 = X^0 \\ X_{n+1} = X_n + h f(X_n) + g(X_n) \Delta W_n \end{cases}$

$$:= W(t_{n+1}) - W(t_n) \sim \sqrt{h} W(0, Id)$$

Def: (Mean-Square error)

$(X_n)_n$ has strong order $\gamma > 0$ if $\forall h$ small enough,

$$\mathbb{E} [|X_n - X(t_n)|^2]^{1/2} \leq C h^\gamma \text{ and } C \ll h, n.$$

Prop: EM has order $1/2$

→ Compare deterministic Euler

proof: super hard

Milstein scheme:

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$$X(t) = X_0 + \underbrace{\int_0^t f(X(s)) ds}_{\approx f(X_0)t + \mathcal{O}(t^2)} + \underbrace{\int_0^t g(X(s)) dW(s)}_{\approx g(X_0)W(t) + \mathcal{O}(\sqrt{t})}$$

$$X(t) = X_0 + g(X_0)W(t) + \mathcal{O}(\sqrt{t})$$

$$\int_0^t g(X(s)) dW(s) \approx g(X_0)W(t) + g'(X_0)(g(X_0)) \int_0^t W(s) dW(s) + o(t)$$

$$\begin{aligned} \text{so } X_{n+1} &= X_n + h f(X_n) + g(X_n)\Delta W_n + g'(X_n)(g(X_n)) \underbrace{\int_{t_n}^{t_{n+1}} W(s) dW(s)}_{\substack{\approx \frac{1}{2}(\Delta W_n^2 - h) \\ \text{Ito's Lemma}}} \end{aligned}$$

Prop: Milstein has strong order 1.

→ numerical experiments

2) Weak error

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→ We do not know W , we want to know the law of X solution of

$$\begin{cases} dX = f(X) dt + g(X) dW \\ X(0) = X^0 \end{cases}$$

Def: a method $(X_n)_n$ has weak order γ if $\forall \phi$ test function (usually ϕ_p) /

$$\left[\begin{array}{l} \text{and } \forall R \text{ small enough such that } T = NR, \\ |\mathbb{E}[\phi(X_n)] - \mathbb{E}[\phi(X(t_n))]| \leq CR^\gamma \end{array} \right.$$

ex: $\phi(x) = x \rightarrow \mathbb{E}$
 $\phi(x) = x^2 \rightarrow \text{Var}$

Langevin $\mathbb{E}[(\cdot)^2] = \text{temperature}$

→ ex invariant measure

Rq: We need $\mathbb{E}[\mathbb{E}[X|Y]] = \mathbb{E}[X] \dots \dots \dots \sim \mathcal{N}(0, Id)$
Thm: EM has weak order 1: $X_{n+1} = X_n + h f(X_n) + \sqrt{h} g(X_n) \tilde{\epsilon}_n$

Proof: Lemma: (a) If $\mathbb{E}[X_0^{2m}] < +\infty, \forall m, \mathbb{E}[X_n^{2m}] \leq C_m < +\infty$

Proof: $X_{n+1} = X_n + h f(X_n) + \sqrt{h} g(X_n) \tilde{\epsilon}_n$

- $|\mathbb{E}[X_{n+1} - X_n | X_n = x]| = |\mathbb{E}[h f(x)]| = |h f(x)| \leq C(1+|x|)h \quad (1)$
- $|X_{n+1} - X_n| \leq R|X_n| + \sqrt{h} |g(X_n)| |\tilde{\epsilon}_n|$
 $\leq C(1+|X_n|)h + C(1+|X_n|)\sqrt{h} |\tilde{\epsilon}_n|$
 $\leq C(1+|X_n|)\sqrt{h} (\underbrace{\sqrt{h}}_{\leq \sqrt{T}} + |\tilde{\epsilon}_n|)$ and $\mathbb{E}[|\tilde{\epsilon}_n|^{2m}] < +\infty, \forall m$

It is $|X_{n+1} - X_n| \leq M_n (1+|X_n|)\sqrt{h}$ and $\mathbb{E}[M_n^{2m}] \leq \underbrace{C_m}_{\neq n} \quad (2)$

• Define $X_{n+1} - X_n = \Delta X_n$

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$$(X_{n+1})^{2m} = (X_n + \Delta X_n)^{2m} = X_n^{2m} + \binom{2m}{1} X_n^{2m-1} \Delta X_n + \sum_{j=2}^{2m} \binom{2m}{j} X_n^{2m-j} \Delta X_n^j$$

I II III

(II) $|\mathbb{E}[(X_n)^{2m-1} \Delta X_n]| = |\mathbb{E}[(X_n)^{2m-1} \mathbb{E}[\Delta X_n | X_n]]|$

(1) $\leq \mathbb{E}[|X_n|^{2m-1} K(1+|X_n|)R]$

$\leq KR(1 + \mathbb{E}[|X_n|^{2m}])$

(III) $\mathbb{E}[|X_n|^{2m-j} |\Delta X_n|^j] \stackrel{(2)}{\leq} \mathbb{E}[|X_n|^{2m-j} M_m^j (1+|X_n|^j) R^{j/2}]$
 $\leq KR(1 + \mathbb{E}[|X_n|^{2m}])$ because $j \geq 2$

Finally, $\mathbb{E}[|X_{n+1}|^{2m}] \leq (1+KR) \mathbb{E}[|X_n|^{2m}]$
 $\leq e^{KR} \mathbb{E}[|X_n|^{2m}]$

$\dots \mathbb{E}[|X_n|^{2m}] \leq \underbrace{e^{KnR}}_{\leq e^{KT} < +\infty} \mathbb{E}[|X_0|^{2m}]$

□

(b) Local error

$$\begin{aligned} \mathbb{E}[\phi(X_1)] &= \mathbb{E}[\phi(x_0 + h f(x_0) + \sqrt{h} g(x_0))] \\ &= \phi(h) + h \phi'(h) + \frac{h}{2} \underbrace{\mathbb{E}[\phi''(g, g)]}_{= \mathbb{E}[\tilde{g}^2] \phi''(g, g)} + O(h^2) \\ &= \phi + h \mathcal{L}\phi + \underbrace{O(h^2)}_{\text{where } \mathcal{L}\phi = \phi'(h) + \frac{1}{2} \phi''(g, g)} \end{aligned}$$

Then $u(x, t) = \mathbb{E}_x[\phi(X(t))]$ is solution of Kolmogorov equation

$$\left[\frac{\partial u}{\partial t} = \mathcal{L}u, u(x, 0) = \phi(x) \right]$$

→ use Itô's formula

$$\mathbb{E}[\phi(X(t))] = \phi(x) + \mathcal{L}\phi(x)t + \frac{1}{2}t^2 \mathcal{L}^2\phi(x) + \dots$$

$$\mathbb{E} \left[|\mathbb{E}[\phi(X_1)] - \mathbb{E}[\phi(X(t))]| \leq Ct^2(1+|x|^k) \right]$$

© Global error

$X^x(t)$ solution coming from x at $t=0$

X_N^x

$$e = \mathbb{E}[\phi(X^x(t_N)) - \phi(X_N^x)]$$

$$= \sum_{i=1}^N \mathbb{E}[\phi(X_{N-i}^x(t_i)) - \mathbb{E}[\phi(X_{N-i+1}^x(t_{i-1}))]]$$

$$= \sum_{i=1}^N \mathbb{E}[\phi(X_{N-i}^x(t_i)) - \mathbb{E}[\phi(X_{N-i}^x(t_{i-1}))]]$$

$\tilde{\Phi}_i(x) = \phi \circ X^x(t_{i-1})$ test function

$$\text{local error gives } |\mathbb{E}[\tilde{\Phi}_i(X_{N-i}^x(t_i))] - \mathbb{E}[\tilde{\Phi}_i(X_{N-i}^x(t_{i-1}))]|$$

$$\leq \mathbb{E}[Cr^2(1+|X_{N-i}^x|^k)]$$

$$\text{so } |e| \leq \sum_{i=1}^N \mathbb{E}[Cr^2(1+|X_{N-i}^x|^k)]$$

$$\leq Cr^2 \sum_{i=1}^N (1 + \mathbb{E}[|X_{N-i}^x|^k])$$

$\leq C$ because of bounded moment

$$\leq Cr^2 N \leq (Cr)$$

□

→ CV course for real E.M.

Example: $dX = aX dW - \frac{a^2}{2} X dt$, $X(0) = 1$

$X(t) = e^{aW(t)}$

$X_{n+1} = X_n + aX_n \sqrt{h} \xi_n - \frac{a^2}{2} X_n h = \left(1 + a\sqrt{h} \xi_n - \frac{a^2}{2} h\right) X_n$

$X_n = \prod_{i=1}^n \left(1 + a\sqrt{h} \xi_i - h \frac{a^2}{2}\right)$

$= 1 + a\sqrt{h} \sum_{i=1}^n \xi_i + O(h)$

$\stackrel{\mathcal{L}}{=} W(nh)$

Extension: Stochastic Runge-Kutta for $dX = f(x) dt + \sigma dW$

$$\begin{cases} Y_i^n = X_n + h \sum_{j=1}^n a_{ij} f(Y_j^n) + d_i \sigma \sqrt{h} \xi_n \\ X_{n+1} = X_n + h \sum_{i=1}^n b_i f(Y_i^n) + \sigma \sqrt{h} \xi_n \end{cases}$$

• bounded moments → OK

• local error → RK conditions: $\sum b_i = 1 \Rightarrow A_0 = \mathcal{L}$
 $\left. \begin{aligned} \sum b_i c_i &= 1/2 \\ \sum b_i c_i^2 &= 1/2 \\ \sum b_i d_i &= 1/2 \end{aligned} \right\} \Rightarrow A_1 = \frac{1}{2} \mathcal{L}^2$

$E[\phi(X_1)] = \phi + h A_0 \phi + h^2 A_1 \phi + h^3 A_2 \phi + \dots$

(a) The WOS algorithm

goal: Solve
$$\begin{cases} h \in \mathcal{C}(\bar{D}, \mathbb{R}) \cap \mathcal{C}^2(D, \mathbb{R}) \\ \Delta h = 0 \text{ in } D \\ h = f \text{ on } \partial D \end{cases} \quad (DP)$$

where D is a bounded open set in \mathbb{R}^d (d large).

Prop: u is harmonic in D iff u satisfies the mean value property,

i.e. $\forall B_r(x) \subset D$,

$$u(x) = \frac{1}{\underbrace{\sigma(\partial B_r(x))}_{\text{measure of } \partial B_r(x)}} \int_{\partial B_r(x)} u(y) d\sigma(y)$$

Rq: \approx Cauchy formula for holomorphic functions

harmonic functions in $\mathbb{R}^2 \stackrel{\approx}{\subseteq}$ holomorphic functions in \mathbb{C}, \dots

Proof: \ominus If $\Delta u = 0$, by Itô formula, where $(W_0 = x)$

$$u(W_t) = u(W_0) + \int_0^t \nabla u(W_s) dW_s + \frac{1}{2} \int_0^t \underbrace{\Delta u(W_s)}_{=0} ds$$

$$\mathbb{E}_x[u(W_t)] = \mathbb{E}_x[u(W_0)] = u(x)$$

If $\tau_{B_r(x)} = \inf \{ t > 0, W_t \in \partial B_r(x) \}$,

with bounded CV then,

$$\mathbb{E}_x[u(W_{\tau_{B_r(x)}})] = u(x)$$

$$= \int_{\partial B_r(x)} u(y) d\mathbb{P}_{W_{\tau_{B_r(x)}}}(y) = \int_{\partial B_r(x)} u(y) \frac{d\sigma(y)}{\sigma(\partial B_r(x))}$$

because $W_{\tau_{B_r(x)}}$ follows a uniform law on $\partial B_r(x)$ by symmetry.

⊆ Analytic roof

(14)

differentiable under \int gives $u \in C^\infty$.

for $\gamma \in \partial B_r(0)$,

$$u(x+\gamma) = u(x) + \gamma \cdot \nabla u(x) + \frac{1}{2} D^2 u(x)(\gamma, \gamma) + o(r^2)$$

$$\int_{\partial B_r(0)} \gamma_i d\sigma = 0 \quad \text{and} \quad \int_{\partial B_r(0)} \gamma_i \gamma_j d\sigma = 0 \quad (i \neq j)$$

$$\circ \circ \circ \quad u(x) = \frac{1}{\sigma(\partial B_r(x))} \int_{\partial B_r(x)} u(x+\gamma) d\sigma(\gamma)$$

mean value property

$$= u(x) \times 1 + 0 + \frac{1}{2} \sum_{i=1}^d \frac{\partial^2 u}{\partial x_i^2}(x) \frac{1}{\sigma(\partial B_r(0))} \int_{\partial B_r(0)} \gamma_i^2 d\sigma(\gamma) + o(r^2)$$

$$\text{but } \frac{1}{\sigma(\partial B_r(0))} \int_{\partial B_r(0)} \gamma_i^2 d\sigma(\gamma) = \frac{1}{d \sigma(\partial B_r(0))} \int_{\partial B_r(0)} \overbrace{\|\gamma\|^2}^{=1} d\sigma(\gamma)$$
$$= \frac{1^2}{d}$$

$$\circ \circ \circ \quad u(x) = u(x) + \frac{r^2}{2d} \Delta u(x) + o(r^2)$$

$$\Rightarrow \boxed{\Delta u(x) = 0}$$

□

Summary: we found: if h solution of $\Delta h = 0$

$$h(x) = \mathbb{E} [h(W_{\tau_{\partial D}(x)})] \\ \sim \mathcal{U}(\partial D(x))$$

Was algorithm:

$$\begin{cases} X_1^x(1) = x \\ X_1^x(n+1) = X_1^x(n) + \lambda d(X_1^x(n), \partial D) U_n \end{cases}$$

where $\lambda \in]0, 1[$ is fixed and $U_n \sim \mathcal{U}(S^d)$
↳ agree mit

→ exp. numérique

Prop: $(X_1^x(n))_n$ CV a.s. to $X_1^x(\infty) \in \partial D$ ("hard")

• $(X_1^x(n))_n$ is a martingale w.r.t. $\mathcal{F}_n = \sigma(U_1, \dots, U_{n-1})$

Thm: let h be the solution of (OP),

$$h(x) = \begin{cases} f(x) & \text{if } x \in \partial D \\ \mathbb{E} [f(X_1^x(\infty))] & \text{if } x \in D \end{cases}$$

sc: $D = \square$

$$f(x, y) = e^x \sin(y)$$

idea: when $d(X_1^x(n), \partial D) < \epsilon$, → stop
and $X_1^x(\infty) \approx \Pi_{\partial D}(X_1^x(n))$

↑
hard for weird geometries D (badly...)

Can/Pro

Prob: (same algorithm for single values (finite diff/elements are better)
but if \dim is huge, finite elements fail (slower and slower
and for the CV algo the same (1/2 for Monte-Carlo)

Ⓐ WOMS

Same with "missing sphere" in space and time

↳ solves the heat equation

→ numerical experiment

Ⓒ MLMC

↳ goal: reduce noise

Ⓓ Stochastic gradient / preserving properties

& Langevin → preserving the invariant measure

OU Stochastic oscillator

$$\begin{cases} dx = y dt \\ dy = -\lambda^2 x dt + dW \end{cases}$$

also ~~dE~~ $d\left(\frac{\lambda^2}{2} x^2 + \frac{1}{2} y^2\right) = \lambda^2 x y dt + y(-\lambda^2 x dt + dW) + \frac{dt}{2}$

also $E\left[\frac{1}{2}(\lambda^2 x^2 + y^2)\right](t) = E\left[\frac{1}{2}(\lambda^2 x_0^2 + y_0^2)\right] + \frac{t}{2}$

à réserver
quels schémas utiliser... ?