

Order conditions for sampling the invariant measure of ergodic SDEs in \mathbb{R}^d or on manifolds

Abstract

WE derive a new methodology for the construction of high order integrators for sampling the invariant measure of ergodic stochastic differential equations subjected to a scalar constraint. For a class of Runge-Kutta type methods, we derive the conditions for the order two of accuracy. Numerical experiments in dimension 3 on the sphere and the torus confirm the theoretical findings. We also discuss a possible extension of the exotic aromatic B-series formalism.

1. Long time approximation of constrained ergodic SDEs

WE consider (Stratonovich) stochastic differential equations in \mathbb{R}^d , subjected to a smooth scalar constraint $\zeta = 0$, that have the form

$$dX = \Pi_{\mathcal{M}}(X)f(X)dt + \Pi_{\mathcal{M}}(X)\Sigma(X) \circ dW, \quad (1.1)$$

where $X(0) = X_0 \in \mathcal{M}$, $\zeta: \mathbb{R}^d \rightarrow \mathbb{R}$, $\mathcal{M} = \{x \in \mathbb{R}^d, \zeta(x) = 0\}$ is a compact smooth manifold or $\mathcal{M} = \mathbb{R}^d$, $\Pi_{\mathcal{M}}: \mathbb{R}^d \rightarrow \mathbb{R}^{d \times d}$ is the orthogonal projection on the tangent bundle of \mathcal{M} , $f: \mathbb{R}^d \rightarrow \mathbb{R}^d$ and $\Sigma: \mathbb{R}^d \rightarrow \mathbb{R}^{d \times d}$ are smooth and W is a standard d -dimensional Brownian motion.

Equations of the form (1.1) appear naturally when studying conservative SDEs, that is, SDEs possessing an invariant H . The solution of conservative SDEs are subjected to the constraint $\zeta = 0$ with $\zeta = H - H(X_0)$. The major motivation of this work appears in computational problems in molecular dynamics with the constrained overdamped Langevin equation (obtained in the particular case where $\Sigma = \sigma I_d$)

$$dX = \Pi_{\mathcal{M}}(X)f(X)dt + \sigma \Pi_{\mathcal{M}}(X) \circ dW, \quad (1.2)$$

with $\sigma \in \mathbb{R}$, $f = -\nabla V$ and $V: \mathbb{R}^d \rightarrow \mathbb{R}$ is smooth. The overdamped Langevin equation is widely used to model the motion of a set of particles subjected to a potential V in a high friction regime. The possible constraints can be induced for example by strong covalent bonds between atoms, or fixed angles in molecules. We refer to [5] for further details on applications and numerical methods for sampling constrained SDEs.

Weak error: A numerical scheme $(X_n)_n$ is said to have local weak order p if for every test function ϕ ,

$$|\mathbb{E}[\phi(X_1)|X_0 = x] - \mathbb{E}[\phi(X(h))|X(0) = x]| \leq C(x, \phi)h^{p+1}.$$

The backward Kolmogorov equation yields

$$\mathbb{E}[\phi(X(h))|X(0) = x] = \phi(x) + h\mathcal{L}\phi(x) + \frac{h^2}{2}\mathcal{L}^2\phi(x) + \dots$$

where \mathcal{L} is the generator of (1.1) and is given by

$$\mathcal{L}\phi = \phi'f - G^{-1}(g, f)\phi'g - \frac{\sigma^2}{2}G^{-1}\text{div}(g)\phi'(g) + \frac{\sigma^2}{2}G^{-2}(g, g'g)\phi'(g) + \frac{\sigma^2}{2}\Delta\phi - \frac{\sigma^2}{2}G^{-1}\phi''(g, g), \quad (1.3)$$

where $g = \nabla\zeta$ and $G = g^Tg$. We compare with the Talay-Tubaro expansion of the integrator

$$\mathbb{E}[\phi(X_1)|X_0 = x] = \phi(x) + h\mathcal{A}_0\phi(x) + h^2\mathcal{A}_1\phi(x) + \dots$$

Then the scheme has weak order p if $\forall j \leq p, \mathcal{L}^j/j! = \mathcal{A}_{j-1}$.

Ergodicity property: there exists a probability density ρ_∞ such that

$$\lim_{T \rightarrow +\infty} \frac{1}{T} \int_0^T \phi(X(s))ds = \int_{\mathcal{M}} \phi(y)\rho_\infty(y)d\sigma_{\mathcal{M}}(y) \quad a.s.$$

where $d\sigma_{\mathcal{M}}$ is the canonical measure on \mathcal{M} induced by the euclidean metric of \mathbb{R}^d .

We call **error of the invariant measure** the quantity

$$e(\phi, h) = \left| \lim_{N \rightarrow +\infty} \frac{1}{N+1} \sum_{n=0}^N \phi(X_n) - \int_{\mathcal{M}} \phi \rho_\infty d\sigma_{\mathcal{M}} \right|.$$

The scheme is of order p for the invariant measure if for every test function ϕ , $e(\phi, h) \leq C(x, \phi)h^p$.

Theorem 1. [3] (related work in \mathbb{R}^d : [2, 1])

Under technical assumptions, if $\mathcal{A}_s^* \rho_\infty = 0$ (in $L^2(d\sigma_{\mathcal{M}})$) for $j = 1, \dots, p-1$, i.e. for every test function ϕ ,

$$\int_{\mathcal{M}} (\mathcal{A}_j \phi) \rho_\infty d\sigma_{\mathcal{M}} = 0, \quad j = 1, \dots, p-1,$$

then the scheme has order p for the invariant measure.

2. High order Runge-Kutta methods for overdamped Langevin in \mathbb{R}^d

WE consider Runge-Kutta methods of the form

$$Y_i = X_n + h \sum_{j=1}^s a_{ij}f(Y_j) + \sigma \sqrt{h}d_i \xi_n, \\ X_{n+1} = Y_s.$$

Theorem 2. [3] (Order conditions in \mathbb{R}^d)

A Runge-Kutta method has weak order 1 if $c_s = 1$. In addition, it has order 2 for the invariant measure if the following 2 conditions are satisfied:

$$\sum_{j=1}^s a_{sj}c_j = \sum_{j=1}^s a_{sj}d_j^2 = 2 \sum_{j=1}^s a_{sj}d_j - \frac{1}{2}.$$

Remark. We find 3 order conditions for weak order 2. There are 11 conditions for the weak order 3 and 6 conditions for the invariant measure.

Example.

The θ -method for solving (1.2) is

$$X_{n+1} = X_n + h(1-\theta)f(X_n) + h\theta f(X_{n+1}) + \sigma \sqrt{h}\xi_n. \quad (2.1)$$

It has order 2 for the invariant measure if $\theta = \frac{1}{2}$ and order 1 else.

3. High order Runge-Kutta methods for constrained overdamped Langevin

WE consider the following class of Runge-Kutta integrators

$$Y_i = X_n + h \sum_{j=1}^s a_{ij}f(Y_j) + \sigma \sqrt{h}d_i \xi_n + \lambda_i \sum_{j=1}^s \hat{a}_{ij}g(Y_j), \\ \zeta(Y_i) = 0 \quad \text{if } \delta_i = 1, \\ X_{n+1} = Y_s, \quad (3.1)$$

where $\delta_i = \sum_{j=1}^s \hat{a}_{ij} \in \{0, 1\}$ and $\delta_s = 1$.

Proposition. If $c_s = d_s = 1$ and $\sum \hat{a}_{sj}d_j = \sum \hat{a}_{sj}\delta_j d_j$, the method is consistent, that is, $\mathcal{A}_0 = \mathcal{L}$.

Example.

The simplest numerical scheme for approximating ergodic integrals on manifolds is the Euler method

$$X_{n+1} = X_n + hf(X_n) + \sigma \sqrt{h}\xi_n + \lambda g(X_{n+1}), \\ \zeta(X_{n+1}) = 0. \quad (3.2)$$

It is a Runge-Kutta method of weak order 1 with the coefficients given by the following Butcher tableau.

$$c | A | \delta | \hat{A} | d = \begin{array}{c|cccccc} 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 1 & 1 & 0 & 1 & 0 & 1 & 1 \end{array}$$

Theorem 3. [4] (Order conditions on the manifold \mathcal{M})

We consider a consistent ergodic Runge-Kutta method of the form (3.1) applied to solve (1.2), then the integrator has order 2 for the invariant measure if the coefficients of the method satisfy 23 order conditions:

$$\sum_{j=1}^s \hat{a}_{sj}d_j = \sum_{j=1}^s a_{sj}d_j, \quad \sum_{j=1}^s a_{sj}c_j = 2 \sum_{j=1}^s a_{sj}d_j - \frac{1}{2}, \quad \dots$$

Remark. We find 25 Runge-Kutta order conditions for weak order 2. These conditions are detailed in [4].

4. Exotic aromatic B-series for the computation of order conditions

TREES have proven to be useful for the study and the construction of high order integrators: Butcher, 1972 and Hairer, Wanner, 1974 (See also Hairer, Wanner, Lubich, 2006 and [3]).

We rewrite our differentials with partitioned aromatic forests (see Chartier, Murua, 2007 and Bogfjellmo, 2015). We denote $F(\gamma)(\phi)$ the elementary differential of a tree γ .

$$F(\bullet)(\phi) = \phi'f \\ F(\circ \bullet)(\phi) = \sigma^2 G^{-1} \text{div}(g)\phi'g \\ F(\circ \bullet \bullet)(\phi) = \sigma^2 G^{-1} \phi''(g, g'f)$$

We also introduce **lianas** and **non-oriented edges** in our forests and call these **exotic aromatic forests**.

$$F(\circ \bullet \bullet)(\phi) = \sum_i \phi''(e_i, e_i) = \Delta\phi \\ F(\circ \bullet \bullet \bullet)(\phi) = \sigma^4 G^{-2}(g, g'g) \sum_i \phi''(g'(e_i), e_i) \\ F(\circ \bullet \bullet \bullet \bullet)(\phi) = \sigma^2 G^{-1}(g, f)(\Delta\phi)'g$$

Example.

The operator \mathcal{L} in (1.3) can be rewritten with exotic aromatic forests as

$$\mathcal{L}\phi = F\left(\begin{array}{c} \bullet \\ \circ \bullet \\ \circ \bullet \bullet \\ \circ \bullet \bullet \bullet \end{array}\right)(\phi).$$

In \mathbb{R}^d , we have $g = 0$, so that the trees with white nodes vanish and \mathcal{L} is given by

$$\mathcal{L}\phi = F\left(\begin{array}{c} \bullet \\ \circ \bullet \end{array}\right)(\phi) = \phi'f + \frac{\sigma^2}{2}\Delta\phi.$$

The operator \mathcal{A}_1 can be expressed with exotic aromatic forests.

$$\mathcal{A}_1\phi = F\left(\begin{array}{c} \bullet \\ \circ \bullet \\ \circ \bullet \bullet \\ \circ \bullet \bullet \bullet \end{array}\right)(\phi).$$

For the θ -method (2.1) in \mathbb{R}^d , we find

$$\mathcal{A}_1 = F\left(\begin{array}{c} \bullet \\ \circ \bullet \\ \circ \bullet \bullet \\ \circ \bullet \bullet \bullet \end{array}\right)(\phi).$$

To compute the order conditions for the invariant measure, we apply multiple integrations by parts to get

$$\int_{\mathcal{M}} (\mathcal{A}_j \phi) \rho_\infty d\sigma_{\mathcal{M}} = \int_{\mathcal{M}} (\mathcal{A}_j^0 \phi) \rho_\infty d\sigma_{\mathcal{M}},$$

where $\mathcal{A}_j^0 \phi$ is a differential operator of order 1 on ϕ .

Lemma 4. The process of integration by parts can be rewritten with exotic aromatic forests as a straightforward procedure on graphs. Moreover $\mathcal{A}_j^0 \phi$ can be expressed with exotic aromatic forests.

For the θ -method (2.1) in \mathbb{R}^d , we find

$$\mathcal{A}_1^0 = \left(\frac{1}{2} - \theta\right) F\left(\begin{array}{c} \bullet \\ \circ \bullet \end{array}\right)(\phi).$$

5. Numerical experiments

By solving numerically the order conditions of Theorem 3, we find a new Runge-Kutta method that has order 2 for the invariant measure. In addition, the method is explicit in f and uses only 3 evaluations of f per step.

To check the numerical order 2 for the invariant measure of this integrator, we apply it on the sphere (with $\zeta(x) = (x_1^2 + x_2^2 + x_3^2 - 1)/2$) and the torus (with $\zeta(x) = (x_1^2 + x_2^2 + x_3^2 + R^2 - r^2)^2 - 4R^2(x_1^2 + x_2^2)$, $R = 3$ and $r = 1$) in dimension $d = 3$ and compare it with the Euler scheme (3.2). We plot the error for the invariant measure versus different timesteps h . In both cases, we observe order 1 for the Euler scheme (3.2) and order 2 for the new Runge-Kutta scheme.

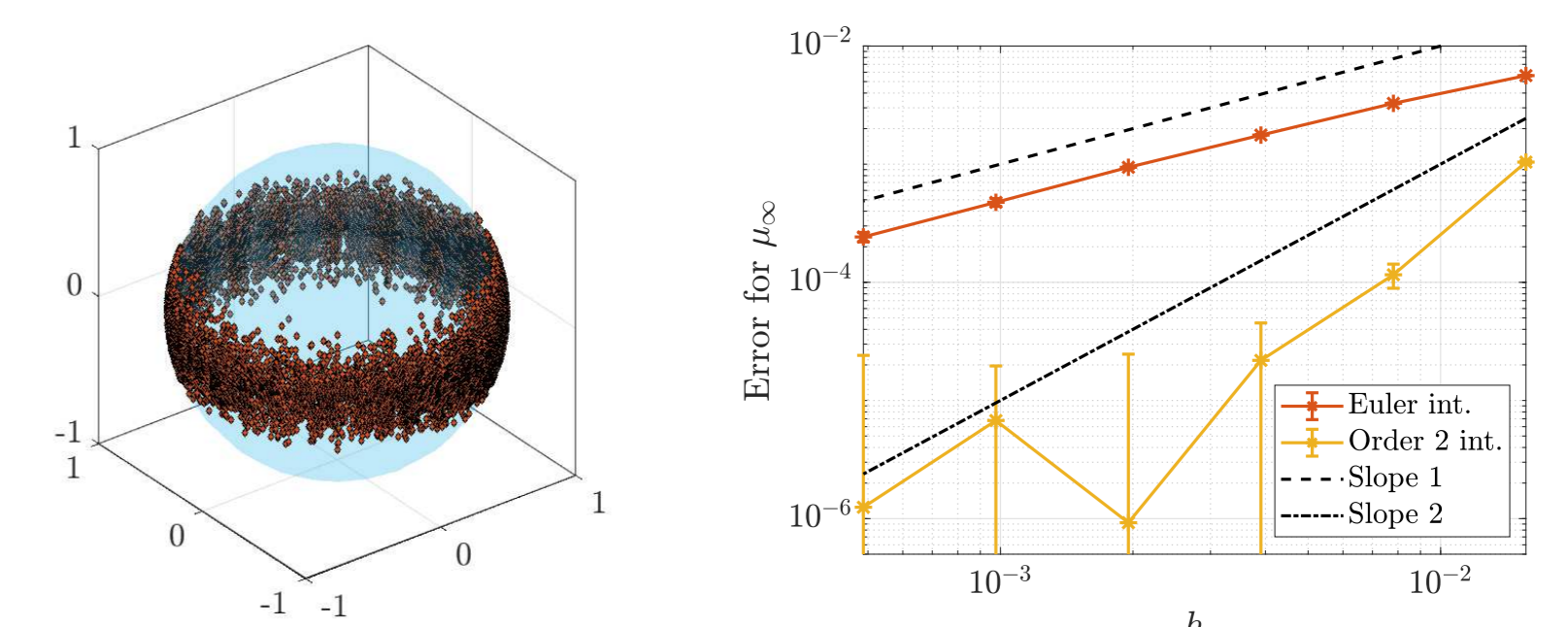


Figure 1: A trajectory of the order 2 method (left) and the convergence curve for the sphere for the invariant measure (right) with $V(x) = 25(1 - x_1^2 - x_2^2)$, $\phi(x) = x_3^2$ and $M = 10^7$ trajectories

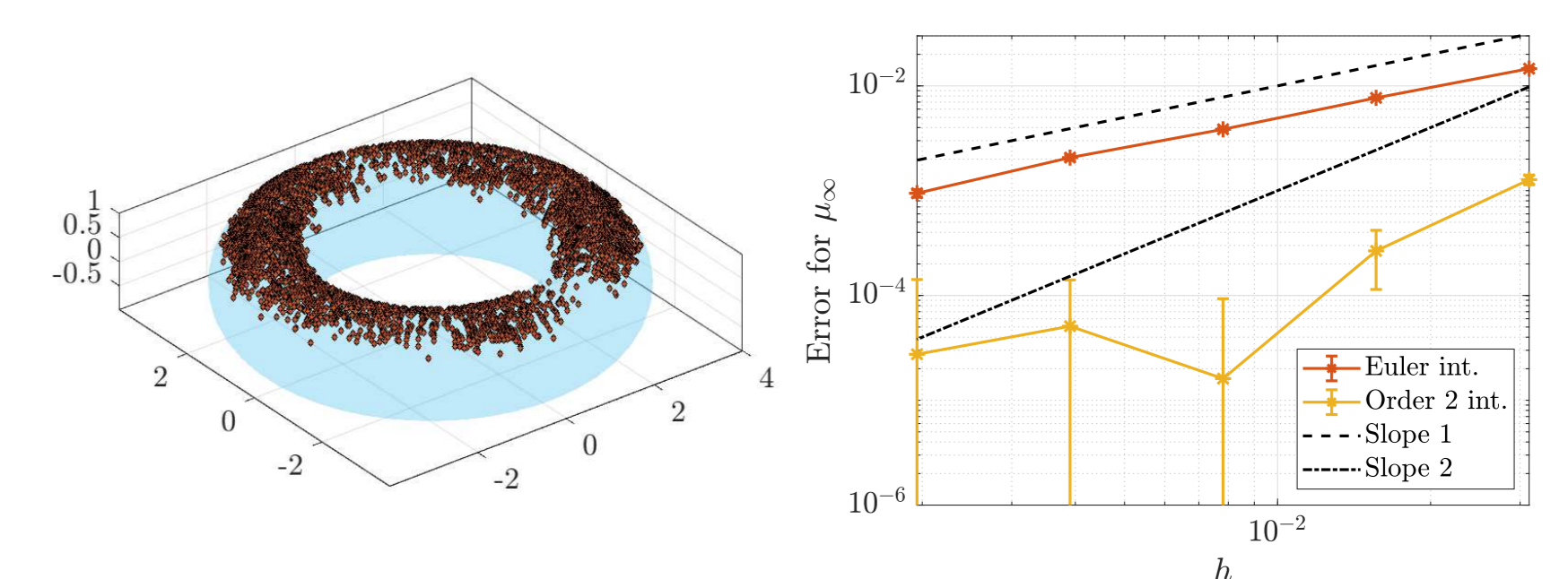


Figure 2: A trajectory of the order 2 method (left) and the convergence curve for the torus for the invariant measure (right) with $V(x) = 25(x_3 - r)^2$, $\phi(x) = x_3^2$ and $M = 10^7$ trajectories

References

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